

Interactive Collaborative Robotics

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Condition: New. Publisher/Verlag: Springer, Berlin | First International Conference, ICR 2016, Budapest, Hungary, August 24-26, 2016, Proceedings | This book constitutes the proceedings of the First International Conference on Interactive Collaborative Robotics, ICR 2016, held in Budapest, Hungary, in August 2016. The 29 papers presented in this volume were carefully reviewed and selected from 48 submissions. A Control Strategy for a Lower Limb Exoskeleton with a Toe Joint.- A Recovery Method for the Robotic Decentralized Control System with Performance Redundancy.- An Analysis of Visual Faces Datasets.- Attention Training Game with Aldebaran Robotics NAO and Brain-Computer Interface.- Conceptual Model of Cyberphysical Environment Based on Collaborative Work of Distributed Means and Mobile Robots.- Control Method for Heterogeneous Vehicle Groups Control in Obstructed 2-D Environments.- Decentralized Approach to Control of Robot Groups During Execution of the Task Flow.- Development of Wireless Charging Robot for Indoor Environment based on Probabilistic Roadmap.- Distributed information system for collaborative robots and IoT devices.- Designing Simulation Model of Humanoid Robot to Study Servo Control System.- Educational Marine Robotics in SMTU.- Human-Machine Speech-Based Interfaces with Augmented Reality and Interactive Systems for Controlling Mobile Cranes.- Human-Robot Interaction using Brain-Computer Interface based on EEG signal decoding.- Interactive Collaborative Robotics and...



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