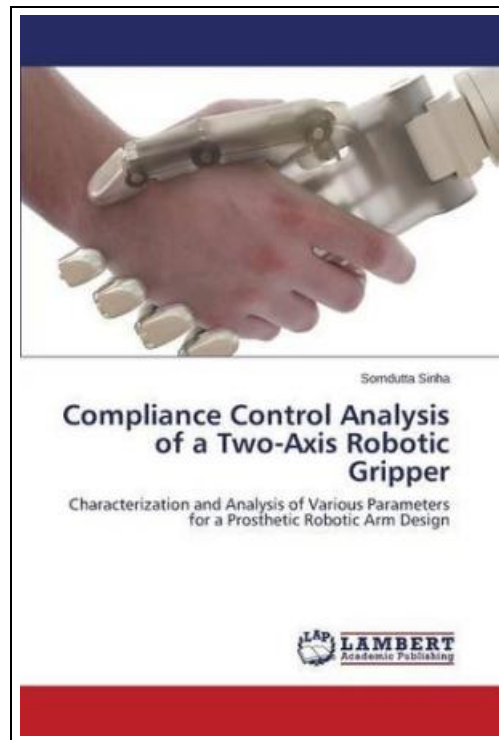


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Condition: New. Publisher/Verlag: LAP Lambert Academic Publishing | Characterization and Analysis of Various Parameters for a Prosthetic Robotic Arm Design | In the presented work, the author has discussed the characterization procedure of artificial human-hand replaced by robotic arm. The book includes the inception of robotic era & its wide possible applications in 3-D block of various shapes & sizes lifting and movements in two-coordinate axis. During the accomplishment of the work, she has tried to explain various control systems required for a dextrous 2-axis robotic arm to function. Simulation works in MATLAB, C++ and BasicX-24 Stamp. Along with this, various established results obtained are highlighted and analyzed analytically. The presented topics also include the detailed mechanism and realization for the manipulation of robot-hand for comfortable operation. The issues related to development of prosthetic hand finds the appropriate substitute under specific conditions in real time situation. The task gets complicated in terms of degree of freedom for movement & accessing the object towards exactness of the need based. The process of fabrication is realized using IIR & FIR digital filters. The system's stability has been given a high priority for the design of such robotic arms to make the same more adaptive in various real time situation. | Format: Paperback | Language/Sprache: english | 120 pp.

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