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Condition: New. Publisher/Verlag: LAP Lambert Academic Publishing | for Remote Multirobot Interaction | A distributed architecture based on the usage of intelligent user interfaces and multiagent systems to facilitate cooperative Internet-based remote interaction with a multirobot system is presented in this book. The proposed system relies on the agent paradigm for dealing with the complexity of cooperative remote interaction systems with multirobots, while taking advantage of intelligent user interfaces for obtaining high degree of naturalness during the interaction sessions. This...

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